

Quantitative Macroeconomics I

Bootcamp 1: Introduction to Matlab

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I thank Tobias Broer, Eustache Elina and Moritz Scheidenberger for useful materials and discussions.

Nice to meet you!

Administrative precisions:



- Fill-in your **contact details** using the spreadsheet !
- **Guidelines to get access to Matlab:**
 1. Download the free trial version of Matlab
<https://www.mathworks.com/campaigns/products/trials.html?country=france>
 2. After registering to the class on course website. Contact IT (support_info@psemail.eu) with proof of registration.
 3. You will get an appointment with IT to set-up your computer.
- **Check your emails** very regularly (updates, schedule, ...)!

What **you** should expect from the tutorials

Format of the tutorials sessions:

Learning Objectives:

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 - ↪ Various **numerical methods**, with advantages and drawbacks
 - ⇒ **QM2 will build on QM1** and will focus on state-of-the-art heterogeneous agent models

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- ⇒ Be able to solve state-of-the-art models (used by central banks, academic research, ...)

What **we** expect from you

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3. Connect the computational methods to economic models! Ask us if you don't see the connection
4. If you notice some typos or mistakes in the slides/assignments, send us directly an email!

We are continuously improving the materials and are putting a lot of effort in teaching this class; typos/mistakes are unavoidable but we want to minimize them.

One more thing...

Some advice

Useful resources (more on the syllabus!)

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- Learning quantitative macro has a **large fixed cost** \Rightarrow Need to invest to benefit from the class
- Help each other to understand the course and methods is the best way to learn

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Useful resources (more on the syllabus!)

- Textbooks: Heer and Maussner *Dynamic GE modelling*, Azzimonti et al *Macroeconomics*
- QuantEcon lecture notes (Sargent, Stachurski): <https://quantecon.org/lectures/>
- Advanced course materials (computational methods)
 - Jesus Fernandez-Villaverde (Princeton): <https://www.sas.upenn.edu/~jesusfv/teaching.html>
 - Fatih Guvenen (Minnesota): <https://www.fatihguvenen.com/phd-computational-methods>

- End-of-semester exam 50% of the final grade
- Around 3/4 problem sets, do be done **by groups of 2** 50% of the final grade
 - ↪ Even if you don't manage to solve the hardest problems, I expect to see some effort
 - Follow the general indications on the website on the formatting of the problem sets

1. Motivation & general takes on software
 2. Matlab basics (matrices, operations)
 3. First exercise: Putting Solow into the computer
 - Arrays, matrices, functions
 - Loops, conditional statements
 - Vectorization, plotting
 3. Linear Interpolation & Vectorization
- Exercise to warm-up!

Why learning numerical techniques?

1. Mathematical sciences always face a trade-off btw. realistic assumptions and solvability

↪ Solving your model numerically *partially* solves this issue

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 - b) In general equilibrium, study the effects of shocks (e.g. taxes) on prices & aggregates

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2. Build an economic intuition by playing with your model
 - a) In partial equilibrium, study the effects of prices on individual decisions
 - b) In general equilibrium, study the effects of shocks (e.g. taxes) on prices & aggregates
3. Makes you able to see the effects of a policy on the **distribution** (HA model)
 - a) Effects of macro policies on inequalities (e.g. fiscal policy)
 - b) Macroeconomic dynamics are heavily modified! (e.g monetary policy)

Why use Matlab?

Pros:

1. Intuitive language
2. Easy to debug: easy to know what you are manipulating
3. Very efficient at handling matrices
4. Widespread use among macroeconomists (e.g central banks)

⇒ Probably not the most efficient language but good enough for simple models

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Cons:

1. Not open source → expensive, code can break across versions in the long run
2. Relatively slow compared to low-level languages...
3. Hard to use together with other languages

⇒ Alternatives: **Julia**, Python – Numba, C++, JAX (*see Fernandez Villaverde:*

https://www.sas.upenn.edu/~jesusfv/Lecture_HPC_5_Scientific_Computing_Languages.pdf)

Divided in four parts:

1. Command window: where you can type and execute commands directly
2. Editor: where you end up writing your code if you want to keep track of it.
 - Note 1: You only use the command window for tests or debugging
 - Note 2: Use comments starting with % for your future readers and for yourself!
 - Note 3: End a line of code with ; if you don't want to see it printed in the command window
→ To run a script : Editor > Run
3. Workspace: all variables, functions, matrices, etc. available to work with
4. Current folder: what scripts you have direct access to
 - Note 4: Keep functions you use in your current folder or in the folder that you have included in your *search path* (Home > Environment > Set Path > Add folders)
 - Search path : files Matlab have access to

- Want to clear the workspace?

```
clear
```

- Want to clear the command window?

```
clc
```

- Want to save your workspace into a file named backup?

```
save backup.mat
```

- Want to load your file backup?

```
load backup.mat
```


- You have access to detailed explanations of any function when writing help or doc followed by the name of the function in the command window. Ex with clear function:

```
help clear
```

```
doc clear
```

- LLMs are quite good at explaining how functions work / giving examples...
 - ↪ ChatGPT, but also open source alternatives: Mistral Codestral, Llama...
 - ⇒ But always check if the answer provided is right!

- Build a scalar:

```
a = 2;
```

- Build a row vector:

```
b = [1 2 3];
```

- Build a column vector:

```
c = [1;2;3];
```

- Build a matrix:

```
d = [1 2; 3 4];
```

- Construct a matrix of 0 of size $m \times n$

```
zeros(m,n)
```

- Construct a matrix of 1 of size $m \times n$

```
ones(m,n)
```

- Construct a matrix of size $m \times n$ of random draws from an uniform distribution in $[0, 1]$

```
rand(m,n)
```

How to navigate in a matrix: indexing 1/2

How to choose specific element(s) in a matrix? Define:

```
h = rand(10,10);
```

- How to pick the element on the 6th row and 7th column:

```
h(6,7)
```

- How to pick all the elements on column 4:

```
h(:,4)
```

Note: In Matlab indexing starts at 1 and not 0! (\neq Python)

- How to pick the first three rows in column 4

```
h(1:3,4)
```

- How to exclude the first and the last column:

```
h(:,2:end-1)
```

Generalization of matrices in more than two dimensions. Ex for an array in 3 dimensions:

```
h = rand(3,5,8);
```

→ Can be visualised as a book of 8 pages with 3×5 elements of each page

A structure array is composed of several fields that can each contain any type of data.

→ Use the dot when naming a variable to create a structure.

```
par.alpha = 0.3;  
par.beta = 0.95;  
par.delta = 0.1;
```

⇒ Creates a structure *par* with all your parameters.

⇒ Useful to **pass parameters in an user-written function** (see last section)

- Standard (matrix or scalar) operators '+', '-', '/', '\', '*' '^'
 - **Element-by-element operators** by adding a **dot** in front of the operator : '.*', './', '.^'
 - Comparison operators
 - equal ==
 - not equal ~=
 - bigger or equal >=
 - smaller or equal <=
- ⇒ A comparison operation will yield either **1** if the condition is true and 0 if not

You can subdivide your code in different sections and run your code only in one specific section

1. Start a line with '%%' to create a section
2. Select a section and click on Editor > Run Section to run it

```
%% 1st section  
A = 1;  
%% 2nd section  
B = rand;
```

Measure the time to run a code: tic toc

You can measure the time a code takes to run using the 'tic toc' function

1. Write tic and jump a line
2. Include the code you want to measure
3. Jump a line and write toc

```
tic  
A = rand(10);  
B = inv(A);  
toc
```

- You can set breakpoints in your code to stop the execution at a specific line
- Click on the left of the line number to set a breakpoint (a red circle appears)
- Run your code and it will stop at the breakpoint
- You can then check the value of your variables in the workspace and run your code line by line using F10
- To remove a breakpoint, click again on the red circle!

More on this next week!

Example: Learning Matlab with the Solow Growth Model

Example 1

Objective: Solve the Solow model numerically to go beyond usual assumptions

Q1. Solve the steady state level of per-capita capital k^* using the first-difference equation

Q2. Find the saving rate that maximizes the steady state level of per-capita consumption c^*

Environment:

The steady state is unique and stable under usual assumptions.

Example 1

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Environment:

- Equations: $Y_t = F(K_t, L_t) = K^\alpha (L_t)^{1-\alpha}$, $I_t = sY_t$, $K_{t+1} = (1 - \delta)K_t + I_t$, $L_{t+1} = (1 + n)L_t$
- Parameters: $\alpha = 0.3$, $\delta = 0.05$, $n = 0.02$
- Exogenous variables: $s \in (0, 1)$, initial value $s = 0.2$
- Endogenous variables: K_t, L_t, Y_t, C_t

The steady state is unique and stable under usual assumptions.

Q1: Solving the steady state of the Solow model

Define $k_t = K_t/L_t$, $y_t = Y_t/L_t$ and $c_t = C_t/L_t$. Then, we have

First difference equation

$$k_{t+1} = \frac{s}{1+n} k_t^\alpha + \frac{(1-\delta)}{(1+n)} k_t := g(k_t)$$

Steady State Condition

k^* is defined by $k_{t+1} = k_t = k^*$

Solution Methods (today):

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⇒ Introduce plots. Need anonymous functions and to build a solver

1.1. Towards a Forward iteration algorithm

Step 1: Define parameters and initial values

```
par.alpha = 0.3;  
par.delta = 0.05;  
par.n = 0.02;  
par.s = 0.2;  
  
k0 = 0.5; % initial value of capital
```

Step 2: We want to iterate on the FD equation $k_{t+1} = g(k_t)$ until convergence.

"Iterate" → apply multiple times the same operation → **loop FOR**

"Until convergence" → need a **stopping criterion** → **conditional statement IF**

1.1. Iterate forward the FD equation...

Write a loop FOR to iterate, and store values of k_t at each iteration

```
% Initialization
```

```
% Iterate on the FD equation
```

```
for
```

```
end
```

1.1. Iterate forward the FD equation...

Write a loop FOR to iterate, and store values of k_t at each iteration

```
% Initialization  
T = 1000;      % max number of iterations  
k = zeros(T,1); % pre-allocate memory  
k(1) = k0;     % initial value of capital  
  
% Iterate on the FD equation  
for  
  
end
```

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Write a loop FOR to iterate, and store values of k_t at each iteration

```
% Initialization  
T = 1000;      % max number of iterations  
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k(1) = k0;     % initial value of capital  
  
% Iterate on the FD equation  
for t=1:T-1  
  
end
```

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Write a loop FOR to iterate, and store values of k_t at each iteration

```
% Initialization
T = 1000;      % max number of iterations
k = zeros(T,1); % pre-allocate memory
k(1) = k0;     % initial value of capital

% Iterate on the FD equation
for t=1:T-1
    k(t+1) = par.s/(1+par.n)*k(t)^par.alpha + (1-par.delta)/(1+par.n)*k(t);
end
```


1.1. Iterate forward the FD equation...until convergence

Write a FOR loop to iterate on the FD equation, and store values of k_t at each iteration

```
% Initialization
for t=1:T-1
    k(t+1) = ( par.s * k(t)^par.alpha + (1-par.delta) * k(t) ) /(1+par.n);

end
```

1.1. Iterate forward the FD equation...until convergence

Write a FOR loop to iterate on the FD equation, and store values of k_t at each iteration

```
% Initialization
for t=1:T-1
    k(t+1) = ( par.s * k(t)^par.alpha + (1-par.delta) * k(t) ) / (1+par.n);
    err = abs(k(t+1)-k(t));
    disp(['Iteration: ', num2str(t), ', Error: ', num2str(err)]);
end
```

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    disp(['Iteration: ', num2str(t), ', Error: ', num2str(err)]);

% Stopping criterion

end
```

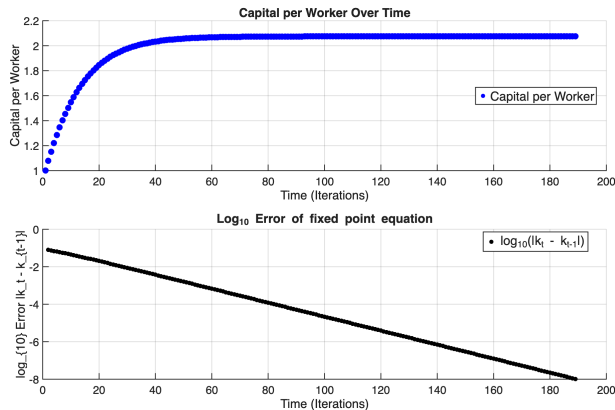
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    err = abs(k(t+1)-k(t));
    disp(['Iteration: ', num2str(t), ', Error: ', num2str(err)]);

% Stopping criterion
if err < 1e-8
    % stop if converged
    break
end
end
```

1.1. Plot the results



- Very simple algorithm!
- Convergence takes 190 iterations at tolerance 10^{-8}
- Takes around 0.008 seconds to run

⇒ Can we do better?

Figure: Convergence of k_t to k^* using forward iteration

1.2. Root-finding method – graphical intuition

Recall: Steady state condition k^* is defined by $k_{t+1} = k_t = k^*$

⇒ Let's plot $g(k) - k$ on a grid of k to find the root graphically

How would you do it?

1.2. Root-finding method – graphical intuition

Recall: Steady state condition k^* is defined by $k_{t+1} = k_t = k^*$

⇒ Let's plot $g(k) - k$ on a grid of k to find the root graphically

How would you do it?

1. Discretize the state space of k (*build a grid* → *vector in matlab*)
2. Compute $g(k) - k$ on the grid
3. Plot the function and find the root

1.2. Plot the Fixed Point function

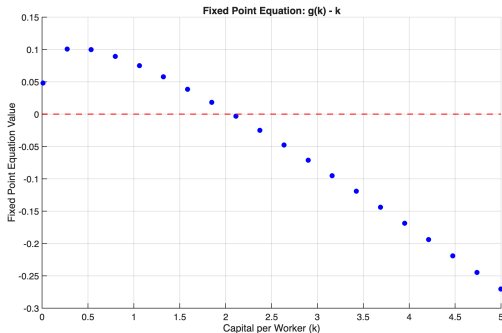


Figure: Plot of the fixed point function $g(k) - k$

```
% grid of 20 points btw. 0.01 and 5
k_grid = linspace(0.01, 5, 20);
```

```
% compute the fixed point function on the grid
fp_eq = @(k, par) (par.s * k.^(par.alpha) + (1 - par.delta) * k) / (1 + par.n) - k;
```

```
% evaluate the function on the grid
```

```
fp_val = fp_eq(k_grid, par);
```

```
% plot the function and the root...
```

```
...
```

⇒ There is clearly only one root that respects boundary conditions (i.e. $k^* > 0$)

Always useful to plot objects of interest in the process... *What can you notice here?*

1.2. Bisection vs Newton methods

Bisection method: *robust method, needs continuity, very slow*

- Start with an interval $[a, b]$ where the function changes sign (i.e. $f(a)f(b) < 0$)
- Compute the midpoint $c = (a + b)/2$ and evaluate $f(c)$
- If $f(a)f(c) < 0$ then set $b = c$, else set $a = c$
- Repeat until convergence

Newton method: *local method, needs a smooth function and a good initial guess, fast (aggressive)*

- Start from an initial guess k_0 and iterate on $k_{n+1} = k_n - FP(k_n) / FP'(k_n)$ until convergence
- Need to compute the derivative of the function $FP'(k)$ (1st order)

1.2. A detour to functions in Matlab

Anonymous functions: useful for simple functions you want to define quickly

```
fp_eq = @(k, par) (par.s * k.^(par.alpha) + (1 - par.delta) * k) / (1 + par.n) - k;
```

User-defined functions: useful for more complex functions you want to keep and re-use

```
% In a separate file named 'my_function.m'
function y = my_function(x, par)
y = (par.s * x.^(par.alpha) + (1 - par.delta) * x) / (1 + par.n) - x;
end
```

⇒ Call it in your main script as:

```
val = my_function(k_grid, par);
```

- What they use as **inputs**:
 - Functions only use the received inputs
 - Scripts have access to the whole workspace
- What they have as **output**:
 - Functions only give the demanded output and erase the rest \Rightarrow local memory
 - Scripts return all variables used in it

Be careful with global variables in Matlab! They can lead to errors and be hard to debug...

1.2. Bisection vs Newton methods – results

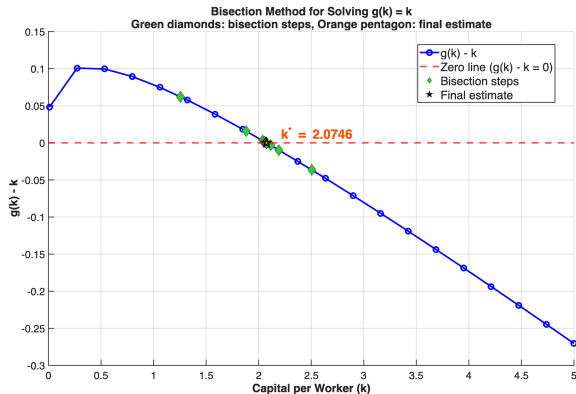


Figure: Bisection method

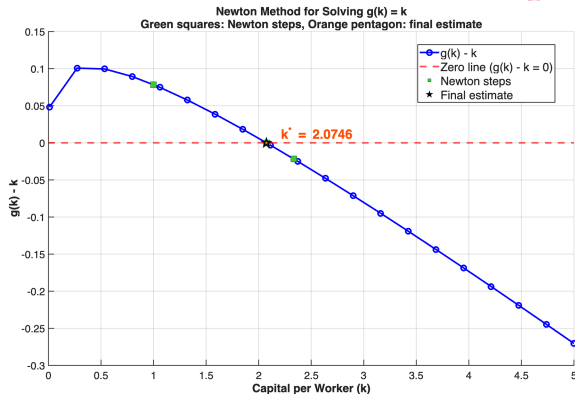


Figure: Newton method

- Bisection: 24 iterations to converge, 0.001 seconds to run (6x faster than forward iteration)
- Newton: 5 iterations to converge, 0.0004 seconds to run (4x faster than bisection)

Q2: Maximizing steady state consumption

Recall: Steady state consumption is defined as $c^* = (1 - s)f(k^*)$

⇒ We want to find the saving rate $s \in (0, 1)$ that maximizes c^*

Two solution methods:

1. **Grid search:** discretize the space of s and find the maximum
2. **Off-grid solver :** use a golden search solver to find the maximum

2.1. Grid search method

Step 1: Discretize the space of s

```
s_grid = linspace(0.01, 0.99, 100); % grid of 100 points between 0.01 and 0.99
```

Step 2: For each s in the grid, compute $k^*(s)$ using bisection and then compute $c^*(s)$

```
c_star = zeros(size(s_grid)); % pre-allocate memory
for i=1:length(s_grid)
    par.s = s_grid(i);
    k_star = bisection(@(k) fp_eq(k, par), 0.01, 5, 1e-8, 100);
    c_star(i) = (1 - par.s) * k_star^par.alpha;
end
```

Step 3: Find the maximum of c^* on the grid

```
c_max, idx = max(c_star); s_opt = s_grid(idx);
```

2.2 Compare results

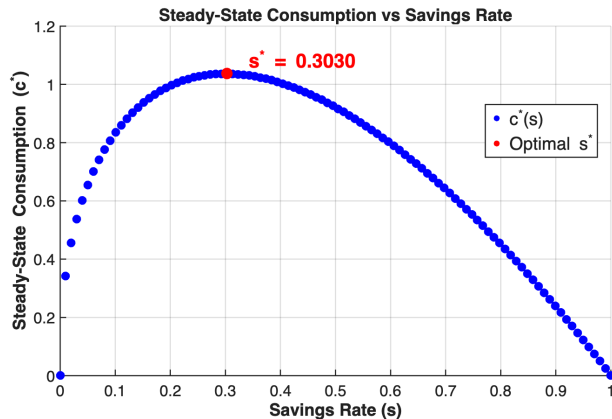


Figure: Maximizing c^* using grid search

- Grid search: over a pre-defined grid
- Golden search: 39 iterations, tolerance level

Golden: faster, control on tolerance, less issues on dimensionality

High-Performance Code

Coding time + Fast execution time + Debugging time

Tricks to write a high-performance code

1. Vectorization
→ Matlab (just as Python / R) prefers vector/matrix operations than codes using loops
2. Write your own functions
→ Example: maximization problem with a solver vs golden algorithm

Remember: "Premature optimization is the root of all evil"... (1) *my code runs properly*, (2) *optimize if needed*

Example 1: Evaluate a function over a discrete interval:

```
a = linspace(0,10,1000);  
f_a = zeros(1,10000);  
tic  
for i=1:size(a,1)  
    f_a = exp(-a(i));  
end  
toc  
tic  
f_a_vec = exp(-a);  
toc
```

Example 2: Element-by-element matrix operation:

```
A = rand(1000,1000);  
B = zeros(1000,1000);  
for i=1:size(A,1)  
    for j=1:size(A,2)  
        B(i,j) = A(i,j)*A(i,j);  
    end  
end  
B_alt = A .* A;
```

Which method works best?

Exercise 1 - do it at home!

Ex 1: Solving the growth model with labor-saving technical progress and CES production function

Consider: $Y = [\alpha K^\rho + (1 - \alpha)(AL)^\rho]^{1/\rho}$, with g the growth rate of A and ρ the elasticity parameter.

1. Define your parameters $\delta = 0.1$, $\alpha = 0.3$, $\rho = 2$, $g = 0.2$, $n = 0.1$, and $k_0 = 1$ using a structure
2. Write a function to solve the Solow model. It must have as
Inputs: saving rate s , the parameters structure and the name of the algorithm to use (forward iteration, bisection or Newton)
Outputs: the steady state capital stock per unit of effective labor $K/(AL) = k^*$,
3. Compute the golden rule saving rate using the Golden search method.
Hint: your golden search function will operate on the function you wrote in the previous step.
4. Build two grids of 50 points each on $n \in [0.01, 0.1]$, $\delta \in [0.05, 0.4]$. Make a surface plot of the steady state k^* as a function of n and δ . Do it for each algorithm specified in question 2. Interpret the result.

Hint: You can build a mesh grid using the function `meshgrid`.

Appendix: Generalities

1. Generalities on plotting
2. Generalities on functions
3. Generalities on conditional statements, loops and try-catch

Objective: We want to plot $z=f(x,y)$ for all possible (x,y)

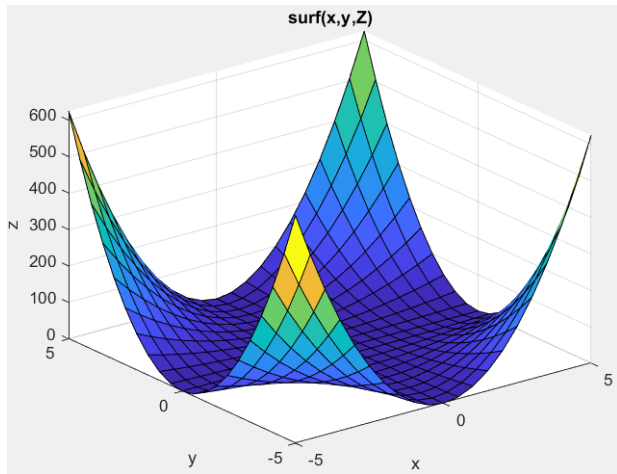
- We need a value of z for each pair (x,y)
- x and y are vectors composed of the elements where the function is evaluated
- Z will be a matrix: for each given x , we need to compute z for all possible y ; and for each given y we need to compute z for all possible x
- To get our matrix Z we need to transform X and Y into matrices

We want to transform x and y into matrices such that applying the transformation $f(.,.)$ to X and Y yields Z

- The function $[X,Y] = \text{meshgrid}(x,y)$ yields two matrices with the first having the rows filled of copies of the vector X and the second one having the columns filled of copies of the vector Y
- Now, applying the transformation $f(.,.)$ to our X and Y will yield Z for all possible pairs (x,y)
- The function $\text{surf}(x,y,Z)$ plots the values in matrix Z as heights above a grid in the x - y plane defined by X and Y

```
x = -5:0.5:5;  
y = -5:0.5:5;  
[X,Y] = meshgrid(x,y);  
Z = (X.*Y).^2;  
figure(2)  
surf(x,y,Z)  
xlabel('x'); ylabel('y'); zlabel('Z');  
title('surf(x,y,Z)')
```

Surface in 3D space: example



- Equally spaced row vector from a to b with n elements:

```
e = linspace(a,b,n);
```

- Equally spaced row vector from a to b with an increment of x (stop before b if the increment does not fit):

```
f = a:x:b;
```

- Logarithmic spaced row vector from 10^a to 10^b with n elements:

```
g = logspace(a,b,n);
```

- Build-in functions are already available `rand(.)`, `diff(.)` etc.
- Two types of user-written functions:
 1. Anonymous functions
 2. Functions (either saved in script or in a separate file)

- The function `max(x)` is one of the most useful function
- Extract the highest value in a vector and gives the index associated

```
xx = rand(1,5);  
[max`xx,i]=max(xx);
```

→ Knowing the index gives the optimal policy function. More on that next class...

From matrix to vector to matrix:

```
% Define a matrix  
A=[1,2,3;4,5,6]  
% Vectorize it (column vector)  
A_vec = A(:);  
% Get back your original matrix  
A_new = reshape(A_vec,2,3);
```

→ Useful to speed up codes to do operations on vectors than going for one cell at a time

- In simulations, it can be useful to always get the same sequence of random numbers
- In that case, you have to set a seed with any integer to the random number generator

```
rng(2);  
x = rand(1,5)
```

Running the code above will always print the following vector:

```
x = [0.4360 0.0259 0.5497 0.4353 0.4204]
```

- The `size(.)` function returns a row vector whose elements are the lengths of the corresponding dimensions of `A`

```
A = [1,2,3;4,5,6];  
size(A)
```

→ Returns a row vector `[2, 3]`

- `size(.,x)` returns a scalar of the length of the dimension `x` of our matrix

```
size(A,2)
```

→ Returns 3

- You can write your own function as a script saved in a .m-file
- Your function must be saved in your current folder or in a folder that you have added to your search path if you want to use it
- The syntax must be the following:

```
function [y1,...,yN] = myfun(x1,...,xM)  
    % interior command block  
end
```

(x1,...,xM) are the inputs to the function and (y1,...,yN) are the outputs that come out of it

Build a function that takes a number and returns the square, the square root, and the factorial

```
function [a,b,c] = fun1(x)
    a = x^2;
    b = x^(1/2);
    c = prod(1:x);
end
```

To use it, write in a script or the command window:

```
fun1(x)
```

with x, any positive integer

- Anonymous functions are functions defined within a script (have a name but not their own .m file)
- Anonymous because they don't have their own .m-file but they do have a name

Example:

```
sqrt = @(x) x.^(1/2); sqrt(144)
```

Once a function is saved in the workspace, it can be easily plotted:

```
fun = @(x) 0.1*x.^2 + sin(x);  
fplot(fun,[-5,5])
```

Loops and Conditional Statements

Syntax example:

```
if x > 10
    % command block 1
elseif x > 5
    % command block 2
else
    %command block 3
```

1. If $x > 10$ then execute command 1
2. If not, then:
 - 2.1 If $x > 5$ then execute command 2
 - 2.2 If not then execute command 3

- Runs the interior code a pre-specified number of times
- At each iteration the loop control variable is increased by one

Loop for : example 1

Generate 50 random number in uniform distribution over $[0, 1]$ and compute the average:

Loop for : example 1

Generate 50 random number in uniform distribution over $[0, 1]$ and compute the average:

```
a = rand(50,1);  
mean_a = 0;  
for i=1:size(a,1)  
    mean_a = mean_a + a(i);  
end  
mean_a = mean_a/size(a,1);
```

Loop for : example 2

Compute the following sum:

$$\sum_{k=1}^{100} \sum_{i=1}^k i$$

Loop for : example 2

Compute the following sum:

$$\sum_{k=1}^{100} \sum_{i=1}^k i$$

```
x=0;  
for k=1:100  
    for i=1:k  
        x=x+i;  
    end  
end
```

Loop for : example 3

Compute 100!

Loop for : example 3

Compute 100!

```
%Method1  
x=1;  
for i=1:100  
    x=x*i;  
end  
%Method2  
prod(1:100);
```

- Runs the interior code as long as a condition is true. Exit the loop when it is false
- Ex-ante the number of iterations is unknown
→ Possible that it will keep running if the condition is always true
- Sometimes useful to include a maximum number of iterations

Loop while : example 1

Compute the limit of the following sequence: $u_{n+1} = -\frac{1}{2}u_n + 3$ with $u_0 = 5$

```
u = 5;  
dif = 10;  
i=0;  
while dif > 1e-8  
    u_prime = -0.5 * u + 3;  
    dif = abs(u_prime - u);  
    i = i + 1;  
    u = u_prime;  
end
```

If you prefer, you can use a maximum number of iterations + break